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✓ COMPUTING LOWER CONFIDENCE
BOUNDS WITH THE LIKELIHOOD RATIO METHOD

by

James B. Lucke

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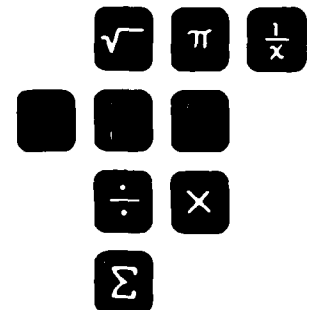
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INTRODUCTION

When expensive, highly reliable systems are produced for a customer, the customer often demands more assurance than a point estimate of the reliability from component by component test data. Many methods [IDS 1979] have been proposed for computing lower confidence bounds for series systems but few methods have been extended to general coherent systems including pseudo-series [IDS 1980], a structure which may be used to model certain types of missiles.

The likelihood ratio method, introduced by Madansky [M] and extended to all coherent systems by Myhre and Saunders [M,S], forms the basis of many methods that have proven useful for series systems [IDS 1979] and pseudo-series [IDS 1980]. The computations of this method are difficult to do by hand for series systems and can be so complicated for other systems as to necessitate a computer program. Subroutines which do these computations for pseudo-series and other types of coherent systems are the focus of this report.

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THE LIKELIHOOD RATIO METHOD

In [M], Madansky introduced the likelihood ratio method of computing confidence intervals for series and parallel systems with binomial component data; this method is based on a result of Wilks that $-2\ln L(r)$ is distributed asymptotically as a chi-squared with one degree of freedom, where $L(r)$ is the likelihood ratio:

$$L(r) = \frac{\sup B(x_1, n_1; p_1)}{\sup B(x_1, n_1; \hat{p}_1)},$$

where $B(x_1, n_1; p_1)$ is the binomial distribution and where the sup in the numerator is over all p such that $r = \prod p_j$ while the sup in the denominator is over all possible values of p and is achieved when p is the maximum likelihood estimate $\hat{p}_1 = x_1/n_1$. In [M] Madansky shows that the numerator can be made a function of δ , a Lagrange multiplier, with $p_1 = (x_1 - \delta)/(n_1 - \delta)$ and $r = \prod p_j$. Hence it is straightforward to solve for $\delta_1 < 0$ and $\delta_2 > 0$ by finding the two solutions of $\ln L(p(\delta)) = -\chi^2(1)/2$, where $\chi^2(1)$ is the 1- γ percentile of the chi-squared distribution with one degree of freedom. The resulting confidence interval is $S(r) = \{r: h(p(\delta_2)) < r < h(p(\delta_1))\}$, where $h(p)$ is the reliability function of the system evaluated at the vector p and $p_1(\delta) = (x_1 - \delta)/(n_1 - \delta)$.

In [M,S] Myhre and Saunders extended this method to general coherent systems with the resulting computations being more complicated than those in the series case. Using the method of Lagrange with multiplier δ to find the sup of the numerator results in the equations:

$$h(p) = r$$

$$D_j \{ \sum \ln B(x_1, n_1; p_1) - h(p) \} = 0, \quad 1 \leq j \leq m \quad \text{where } h(p)$$

is the reliability function of the coherent system and $p = (p_1, p_2, \dots, p_m)$ is the vector of component reliabilities. Myhre and

Saunders show that under certain conditions p is a decreasing function of δ ($\delta > 0$) and exists as a fixed point of a contractive map. Representing this fixed point as $p(\delta)$, $\ln(L(p)) = -\chi^2(1)/2$ may be turned into an equation in δ . As $\ln\{L(p(\delta))\}$ is decreasing in δ , we can bracket $-\chi^2(1)/2$ by incrementing from zero. Then using a technique like the secant method to solve for δ we may find the confidence interval $[R, 1]$, where $R = h(p(\delta))$.

In practice, it turns out that the contractive map may be sensitive to changes in δ near the solution and also may be erratic when the map is started far from the fixed point. The present subroutines used to calculate the confidence intervals are written to extrapolate (or interpolate) to a guess at the new fixed point each time a new δ is used. By doing this the programs have run efficiently and trouble-free.

The Subroutines for General Coherent Systems

There are two subroutine packages, one for general coherent systems and another for pseudo-series systems only. Each package has three subroutines, LRSUB(PLRSUB), POSDEL, AND CONMAP, as well as two functions, XLAMBDA and RELFUN. THEY are written in fortran 77 and run on the CLAREMONT COLLEGES VAX computer when combined with a driving program that sets up the data. The subroutines in the package for general coherent systems and RELFUN share a common block of data that contains the structure of the system, the test data, and the binomial component test data:

Structure of the System

ORDER is the number of distinct components in the system

ITYPE is a parameter of the type of system

1:series

2:parallel

3:k out of n

Binomial Test Data

WINS(I) is the vector of number of successful trials for each component

TRIALS(I) is the vector of number of times each component was tested.

Common Computational Variables

DELTA is the lagrange multiplier

OLDLAM is the value of the function $\Lambda(p_i)$ in $[M, S]$ for the present delta.

PDELTA(I) is the vector of $p_1(\delta)$'s.

PTILDE(I) is the vector of maximum likelihood estimates of the p_1

LRSUB sets up the variables and calls POSDEL three times to compute 80,85, and 90% lower confidence bounds. POSDEL solves the equation $(p(\delta)) = -\chi^2(1)/2$ by incrementing δ until the solution is bracketed and then interpolating to the solution. POSDEL calls CONMAP to get $p(\delta)$ for each δ and uses XLAMBDA to compute $\Lambda(p(\delta))$ once $p(\delta)$ is known. When the equation is solved, control returns to LRSUB from POSDEL and LRSUB computes the bound by plugging the solution vector $p(\delta)$ into RELFUN, the reliability function of the system.

LRSUB

LRSUB is the subroutine that drives the programs that compute 80,85,and 90% lower confidence bounds for general coherent systems using the likelihood ratio method. LRSUB sets up CHISQ(3) as $\chi^2(1)$ for the three levels; sets up $p=.1 \min\{WINS(I): 1 < I < ORDER\}$ to be used as an increment of DELTA in POSDEL; and initializes $PDELTA(I) = PTILDE(I) = WINS(I) / TRIALS(I)$. Then LRSUB calls the subroutine POSDEL once for each of the three confidence levels with the appropriate $Q = -\chi^2(1)/2$; computes the bound by using RELFUN and the returned PDELTA; and stores the computed bounds in LCB(I), I=1,3. LRSUB calls POSDEL, while POSDEL calls CONMAP and XLAMBDA.

POSDEL

POSDEL receives the arguments (P,Q) and uses DELTA and the other variables in the common block to solve $(p(\delta)) = \text{XLAMBDA}(\text{PDELTA}) = Q = -\chi^2(1)/2$ as an equation in $\delta = \text{DELTA}$, where PDELTA is a vector of length ORDER determined by CONMAP for each DELTA. POSDEL takes into account the sensitivity of the contractive map in CONMAP and the need for computational efficiency by extrapolating (or interpolating) from the previous values of PDELTA to get a new PDELTA which corresponds to the new DELTA which is sent to CONMAP.

To keep the solution process clear, POSDEL is written in two parts: the first part to bracket Q by finding successive DELTA such that $\text{XLAMBDA}(\text{DELTA} - \text{GAP}) > Q > \text{XLAMBDA}(\text{DELTA})$; and the second part uses the secant method to find a DELTA such that $|\text{XLAMBDA}(\text{DELTA}) - Q| < .001$. To keep track of the past results, enabling us to extrapolate and interpolate for PDELTA, LWBD(I), and UPBD(I), $I=1, \text{ORDER}$ are set up to contain the PDELTA's that gave the closest upper and lower bounds on Q (LWBD(I) is initialized as 0.0 and UPBD(I) as x_1/n_1 for the first bound and as the solution to the last bound for the second and third bounds).

In part one DELTA is incremented by the value of GAP, which is initially the value of P, sent by LRSUB, and for each new DELTA the vector of PDELTA's is found by CONMAP and OLDLAM is computed by XLAMBDA. Part one iterates through values of DELTA until $Q > \text{OLDLAM}$ ([M,S] shows that XLAMBDA is a decreasing function of DELTA). Once we have PDELTA for one DELTA, we extrapolate for a guess at the next PDELTA so that it corresponds to the new $\text{DELTA} = \text{DELTA} + \text{GAP}$; let $p_1 = P(\delta_1)$, $p_2 = P(\delta_2) = P(\delta + \Delta)$ and assume $P(\delta)$ is linear with $p_3 = P(\delta_2 + \Delta)$. Then $p_3 - p_2 = \text{slope} * \Delta = (p_2 - p_1) / \Delta * \Delta$ and $p_3 = 2p_2 - p_1$. Thus the PDELTA sent

to CONMAP is given as

$PDELTA(I) = 2 * UPBD(I) - OLP(I)$, $1 < I < ORDER$ where OLP is the PDELTA from the previous step.

If CONMAP fails when called in part one , GAP is halved so that POSDEL will approach the solution region more slowly. An analysis similiar to the above shows that the extrapolated PDELTA should then be:

$PDELTA(I) = 3/2 * UPBD(I) - 1/2 * OLP(I)$, $1 < I < ORDER$. To keep LWBD and UPBD correct they are updated (after saving UPBD in OLP) before completing the loop. Until Q is bracketed the new PDELTA returned by CONMAP is saved in UPBD while PDELTA is stored in LWBD when $OLDLAM < Q$ and the program moves to part two.

Upon entering part two , Q is bracketed and hence we may estimate the solution by the interpolation:

$\delta = RR(\delta_2 - \delta_1) + \delta_1$ where $RR = (Q - \lambda_1) / (\lambda_2 - \lambda_1)$. Using the same interpolation $p(\delta) = RR(p_2 - p_1) + p_1$ or $PDELTA(JJ) = UPBD(JJ) + RR * (LWBD(JJ) - UPBD(JJ))$, $1 < JJ < ORDER$. Once DELTA and PDELTA are set up , CONMAP is called and if it does not fail LWBD and UPBD are updated depending on whether the new OLDLAM is less than Q or larger than Q. If CONMAP fails in part two , RR is halved and CONMAP tried again until CONMAP works or has failed nine times (CONMAP works most easily if it does not have to find PDELTA corresponding to a large change in DELTA). DELSAV and DL are also updated before a new interpolation is completed. The loop in part two is thus implementing the secant method and continues until $!Q - OLDLAM! < .001$ at which time control returns to LRSUB where the bound is computed.

CONMAP

CONMAP receives as arguments FAIL, UPBD, LWBD, and GAP, and uses DELTA and the other variables in the common block to compute the fixed point of the contractive map $A((p_i), \delta)$ of Theorem 2-4 of [M,S]: if $(q_i) = A((p_i), \delta)$, and if $a_j(p) = p_j * D_j h(p)$ then $q_j = (x_j - a_j(p)) / (n - a_j(p))$. In [B,P] it is shown that $D_j h(p) = h(p_0) - h(p_1)$, where p_1 is the vector of p_i 's with $p_j = 1$ and p_0 is the same vector with $p_j = 0$. In the program $AJP = A_j(p)$ for each j and $q_j = A(J) = (WINS(J) - DELTA * AJP) / (TRIALS(J) - DELTA * AJP)$. This is not possible if $WINS(J)$ is less than $DELTA * AJP$ and in that case $A(J)$ is left at the previous value (which is $PDELTA(J)$) during the first time through CONMAP). If the new value of $A(J)$ is not in the interval $[UPBD(J), LWBD(J)]$ it is set equal to $(PDELTA(J) + BD) / 2$ where BD is the bound it exceeded.

As the new $A(J)$ are computed, DIST is updated so that it is the distance between the new and old vector values of the contractive map. The map fails if this distance doesn't contract at each step, which is the result if $DIST > DIST2$. Otherwise $DIST2$ is updated and the process continues until we find a fixed point ($DISTTOL = .0005$) and CONMAP returns successfully. $HOLD(I)$ is used to save the initial value of $PDELTA$ to be returned if the contractive map fails. If GAP is small ($GAP < .00001$), $PDELTA$ is determined by averaging $UPBD$ and $LWBD$ since little change can be expected from the contractive map in such a case.

RELFUN

RELFUN is a subfunction that computes the reliability of the given type of system. ITYPE determines the type of system: ITYPE = 1, 2, or 3 if the system is respectively series, parallel, or k out of n system. This function takes a vector of probabilities, PROB, as its argument and computes the reliability using the appropriate formula:

ITYPE=1: series system; $r = \prod \text{prob}(i)$

ITYPE=2: parallel system: $r = 1 - \prod (1 - \text{prob}(i))$

ITYPE=3: k out of n system : $r = \sum E(i; n; p)$,

where $E(i; n; p)$ is the probability of exactly i successes out of n

```

ty
C***** THIS IS THE SUBROUTINE LRSUB *****
C      IT RUNS THE LIKELIHOOD RATIO METHOD
C      IT DOES NOT ADJUST THE FAILURES
C      IT WORKS FOR ALL SYSTEMS
C      WHOSE RELIABILITY FUNCTION CAN BE WRITTEN IN RELFUN
C      NOW ON VAX. 2/23/80
C      ALL IS WORKING WELL WITH THE
C      SUBROUTINES POSDEL,CONMAP
C*****

```

```

      SUBROUTINE LRSUB(LCB)
      DIMENSION CHIISQ(3)
      INCLUDE 'lrcmr.for'
      INTEGER ORDER
      REAL LCB(3)
      DATA CHIISQ/.709, 1.074, 1.642/
C**** P GIVES US AN INITIAL INCREMENT BY WHICH WE CHANGE
C**** DELTA TO LOCALIZE ITS VALUE
      P=1.E15
      DO 40 I=1,ORDER
      IF(WINS(I).LE.P)P=WINS(I)
      PTILDE(I)=WINS(I)/TRIALS(I)
      PDELTA(I)=PTILDE(I)
40      CONTINUE
      P=P/10.0
      DELTA=P
      OLDLAM=0.0
      DO 50 I=1, 3
      Q=-1.0*CHIISQ(I)/2
      CALL POSDEL(BOUND,P,Q)
      BOUND=RELFUN(PDELTA)
      LCB(I)=BOUND
50      CONTINUE
      write(23,1514)(LCB(I),I=1,3)
1514 format(2x,'The Bounds are :',3(f8.5,2x))
      RETURN
999      END

```

```

C***** END OF LRSUB *****

```

```

C
C
C
C
C
C

```

```

      SUBROUTINE POSDEL ITERATES THROUGH VALUES FOR DELTA PLUS

```

```

C***** POSDEL *****
C      POSDEL HAS TWO MAIN parts: in part 1 the value
C      of delta is incremented, with conmap finding
C      the vector of P(i)s, until q has been bracketed.
C      Once a vector of P(i)s is known we extrapolate
C      to set a new vector to start conmap with (the vector
C      corresponds to the new value of delta). This makes
C      conmap less likely to fail. If conmap fails the size
C      of the increment for delta is halved.
C      Part 2 interpolates to get a new delta and also
C      interpolates the P(i)s to get a corresponding vector
C      to start conmap. The interpolation is made possible
C      by storing the P(i)s that correspond to the upper
C      and lower bounds on Q.
C      JBL 3/6/80
C *****

```

```

      SUBROUTINE POSDEL(BOUND,P,Q)
      INCLUDE 'lrcmr.for'

```

```

      DIMENSION UPBD(100),OLP(100)
      REAL LWBD(100)
      INTEGER ORDER
      LOGICAL FAIL
C***** INITIALIZING *****
      GAP=P
      DO 121 I=1,ORDER
        LWBD(I)=0.0
        UPBD(I)=PDELTA(I)
121    CONTINUE
      FAIL=.FALSE.
C***** PART 1 *****
C START OF THE SEARCH FOR A SOLUTION REGION BY
C INCREMENTING DELTA BY GAP UNTIL THE SOLUTION IS BRACKETED
C
      DO 20 J=1,200
        OLAMB=OLDLAM
        DELSAV=DELTA
        DELTA=DELTA+GAP
          IF(J.GT.1) THEN
C          ***** here we extrapolate for pdelta *****
            DO 1042 JJ=1,ORDER
              PDELTA(JJ)=2*UPBD(JJ)-OLP(JJ)
              IF(FAIL)PDELTA(JJ)=1.5*UPBD(JJ)-.5*OLP(JJ)
1042          CONTINUE
            END IF
          CALL CONMAP(FAIL,UPBD,LWBD,GAP)
1044          IF(FAIL) THEN
C          ----- block 1-----
            TYPE 9870
9870          format(' conmap failed ')
            DELTA=DELTA-GAP
            GAP=GAP/2.0
C          ---- block 2 -----
            ELSE
              OLDLAM=XLAMB(OLAMB,PTILDE,PDELTA,ORDER)
d          rel=reldfun(pdelta)
d          write(5,1111) delta,oldlam,q,rel
d          write(5,1112) (pdelta(ITST),ITST=1,order)

1111          format(2x,4f10.4,'##',/,8f6.4)
1112          format(f8.4)

C          ++++++
C          IF(ABS(OLDLAM-Q).LT..001) RETURN
C          ++++++
            DO 19 JJ=1,ORDER
              OLP(JJ)=UPBD(JJ)
              IF(OLDLAM.LT.Q) LWBD(JJ)=PDELTA(JJ)
              IF(OLDLAM.GT.Q) UPBD(JJ)=PDELTA(JJ)
19          CONTINUE
              IF(OLDLAM.GT.Q)OLAMBU=OLDLAM
C          -----
C          **** THIS IS OUR GOAL FOR THIS PART
              IF(OLDLAM.LT.Q) GOTO 30
C          ----- end of block 2 -----
            END IF
20          CONTINUE
C          -----
          WRITE(5,2)
2          format(4x,'No solution after 100 steps in part 1.')
          BOUND=.01
          RETURN
C***** END OF PART 1 *****
C

```

```

C THIS IS THE START OF THE SECTION THAT SOLVES FOR
C DELTA USING THE REGULA FALSI METHOD
C AND we interpolate for the pdelta (between upbd
C and lwbd.).
C*****

C **** INITIALIZE THE VARIABLES *****
30   deltau=delta-gap
    deltal=delta
    olamb1=oldlam
C -----
C DO 40 J=1,100
C **** here we interpolate for delta and pdelta ****
    IF(.NOT.FAIL) RR=(Q-OLAMBU)/(OLAMBL-OLAMBU)
    IF(FAIL) RR=RR/2.0
    DELTA=DELTAU+RR*(DELTAL-DELTAU)
    DO 1313 JJ=1,ORDER
    PDELTA(JJ)=UPBD(JJ)+RR*(LWBD(JJ)-UPBD(JJ))
1313 CONTINUE
    GAPP=DELTAL-DELTAU
C -----
C CALL CONMAP(FAIL,UPBD,LWBD,GAPP)
    IF(.NOT.FAIL) THEN
C ----- block 1 -----
        IT=0
9871 OLDLAM=XLAMBD(TRIALS,PTILDE,PDELTA,ORDER)
C ++++++
C IF((OLDLAM-Q).lt..001)RETURN
C ++++++
C IF(olaml.lt.Q) THEN
C --- block a-----
    DELTAL=DELTA
    OLAMBL=OLDLAM
    do 38 JJ=1,order
    LWBD(JJ)=PDELTA(JJ)
38 CONTINUE
C -----
C ELSE
C --- block b -----
    DELTAU=DELTA
    OLAMBU=OLDLAM
    DO 39 JJ=1,ORDER
    UPBD(JJ)=PDELTA(JJ)
39 CONTINUE
C -----
C END IF
C **** CHECK TO SEE IF DELTAS ARE TOO CLOSE ****
    IF((deltal-deltau).lt.1E-5) then
    WRITE(5,3)
3   FORMAT(' DELTA CAN NO LONGER BE signif. INCREASED.')
    RETURN
    END IF
C -----
C ELSE
C -----CRISIS ROUTE -----
    IT=IT+1
    IF(IT.gt.9)stop
C END IF
C -----
40 CONTINUE
    WRITE(5,1)
1   FORMAT(' NO SOLUTION FOUND AFTER 100 times thru part 2')
    BOUND=.01
    RETURN
C ----- unsuccessful exit -----

```



```

C
C      THIS COMPUTES THE CONTRACTIVE MAP
C      OF EQN. 2.1 IN MYHRE-SAUNDERS PAPER.
C      UPDATED TO JUST KEEP A(J) BETWEEN THE
C      BOUNDS ON PDELTA.      JBL      2/16/80
C      THIS VERSION IS FOR GENERAL COHERENT
C      SYSTEMS AND IS USED BY LRSUB. JBL 5/22/80
C***** CONMAP *****

      SUBROUTINE CONMAP(FAIL,UPBD,LWBD,GAP)
      INCLUDE 'lrcomp.fcr'
      INTEGER ORDER
      LOGICAL FAIL
      DIMENSION HOLD(100),A(100),UPBD(100)
      REAL LWBD(100)
      FAIL=.FALSE.
      TOL=.0005
C      **** IF GAP IS VERY SMALL WE SIMPLY AVERAGE THE BOUNDS OF PDELTA.
      IF(GAP.LT.1E-4)THEN
      DO 999 J=1,ORDER
      PDELTA(J)=(LWBD(J)+UPBD(J))/2.0
999    CONTINUE
      RETURN
C      -----
      ELSE
C      MAIN PART OF WORK.
      DO 10 J=1,ORDER
      HOLD(J)=PDELTA(J)
      A(J)=HOLD(J)
10     CONTINUE
C***** SOLVE THE CONTRACTIVE MAP
      DIST2=1.0
100    DO 40 ICE=1,1000
      DIST=0.
C      --- compute delay for each component -----
      DO 30 J=1,ORDER
      IF(WINS(J).EQ.TRIALS(J))A(J)=1.
      IF (A(J).NE.1.0) THEN
      temp=Pdelta(J)
      pdelta(J)=0.0
      p0=relfun(pdelta)
      pdelta(J)=1.0
      p1=relfun(pdelta)
      pdelta(J)=temp
      delay=delta*pdelta(J)*(p1-p0)
C      *** IF DELAJ>=WINS, DO NOT ASSIGN A(J), IT WILL BE NEG.
      IF(DELAY.LT.WINS(J)) THEN
      A(J)=(WINS(J)-DELAY)/(TRIALS(J)-DELAY)
C      *** WE MUST MAKE SURE A(J) STAYS BETWEEN THE BOUNDS
      IF(A(J).LT.LWBD(J))A(J)=(PDELTA(J)+LWBD(J))/2.0
      IF(A(J).GT.UPBD(J))A(J)=(PDELTA(J)+UPBD(J))/2.0
      DIST=DIST+ABS(A(J)-PDELTA(J))
C      -----
      END IF
30    CONTINUE
C      ----- new pdeltas are done -----
      DO 70 L=1,ORDER
      PDELTA(L)=A(L)
70    CONTINUE
C      ***** IF APPROXIMATIONS HAVE CONVERGED ENOUGH, WE STOP ITERATING.
      DIST=DIST/ORDER

```

```

C      ++++++
C      IF(DIST.LT.TOL) RETURN
C      ++++++
C      ***** IF DIST IS INCREASING, CONMAP FAILS AND WE GO TRY
C      ***** ANOTHER DELTA AND KEEP THE OLD PDELTA'S.
C      IF(DIST.LT.DIST2) THEN
41         DIST2=DIST
C         -----
C         ELSE
C         DO 50 J=1,ORDER
50         PDELTA(J)=HOLD(J)
C         FAIL=.TRUE.
C         RETURN
C         -----
C         END IF
40     CONTINUE
C     END IF
C     END
C*****
$

```

Subroutines for Pseudo-series Systems

The subroutine package for pseudo-series systems consists of three subroutines, PLRSUB, POSDEL, and CONMAP as well as two functions, XLAMBDA and RELFUN. These subroutines perform the same tasks as those in the other package, but are specialized for pseudo-series since the reliability function of a pseudo-series is given as $h(p) = \sum_j w_j \prod p_j^{\alpha_{ij}}$ where $\alpha_{ij} > 0$ if the i -th component is in the j -th subpopulation and $\alpha_{ij} = 0$ if not. See [IDS 1980] for a derivation of this function that shows how it models some missile systems. From this form of the reliability function it follows that $D_k h(p) * p_k = \sum_j w_j \alpha_{kj} p_j^{\alpha_{kj}}$. In this package the part of the common block describing the structure of the system is expanded so that it contains:

ORDER is the number of distinct components in the system.

LLL is the number of subpopulations in the system.

W(J) is the vector of subpopulation weights.

AL(I) is the vector of component exponents.

IG(I,J) is the matrix of indices for the inclusion

of component j in the i -th subpopulation. The rest of the common block is the same as in the other package.

PLRSUB performs exactly the same role in this package as LRSUB does in the other package. POSDEL is the same as the other POSDEL, while CONMAP is almost the same except for the lines computing AJP. Since $a_k(p) = p_k * D_k h(p) = \sum_j w_j \alpha_{kj} p_j^{\alpha_{kj}}$ and is not $p_k (h(p_j) - h(p_j))$, AJP is computed directly in this version of CONMAP. XLMBDA is the same as before, but of course RELFUN is the implementation of the pseudo-series reliability with no possibility of modelling anything else.

```

ty Pjustlr.for
C***** THIS IS PJUSTLR *****
C
C          REVISED 2/8/80   JBL
C*****
      REAL LCB(3)
      INTEGER ORDER
      INCLUDE 'lrcomp.FOR'
      CALL PGETDAT(WINS)
      CALL PLRSUB(LCB)
999      END
C *****
C
C
C
C ***** SUBROUTINE PGETDAT *****
C *****
C      THIS WILL SET UP THE DATA FOR COMPUTING LIKELIHOOD
C      RATIO LOWER CONFIDENCE BOUNDS FOR PSEUDO-SERIES BY
C      ASKING FOR THE INPUT AND OUTPUT FILES AND OPENING THE FILES.
C      THE INPUT FILE MUST CONTAIN IN ORDER:
C          NUMBER OF UNIQUE COMPONENTS (N) AND SUBSYSTEMS (L)
C          WEIGHTS FOR THE L SUBSYSTEMS
C          EXPONENTS FOR EACH UNIQUE COMPONENT
C          NXL MATRIX INDICATING WHICH OF THE
C          L SUBSYSTEMS EACH COMPONENT IS
C          COMMON TO.
C          SUCCESSES AND TRIALS FOR COMPONENTS
C          1,2,...,N
C *****
C ***** SUBROUTINE PGETDAT(OWINS)
C          DIMENSION OWINS(100)
C          INTEGER ORDER
C          DOUBLE PRECISION FILNAM
C          INCLUDE 'lrcomp.FOR'
15      FORMAT(2i2)
      TYPE 1313
1313      FORMAT(' WHAT FILE HAS THE SYS. DATA ', $)
      accept 1314, FILNAM
1314      FORMAT(A10)
      OPEN(UNIT=22,name=filnam,ACCESS='sequential',type='old')
      TYPE 1315
1315      FORMAT(' WHAT FILE SHOULD THE OUTPUT
2 BE FILED IN? '$)
      accept 1314, FILNAM
      open(unit=23,name=filnam,access='sequential',type='new')
      READ(22,15)ORDER,LLL
      IF (ORDER.EQ. 0) GOTO 30
      READ(22,413)(W(I),I=1,LLL)
413      FORMAT(12F)
      write(23,1511)
1511      format(2x,'THE FOLLOWING IS RUN ON THE VAX',/,
1      ,2x,'using JBEPOS,JBCONM .')
      call IDATE(ID1,id2,id3)
      write(23,1512) id1,id2,id3
1512      format(2x,'The date is ',i3,':',i3,':',i3)
      write(23,1513)ORDER,LLL
1513      format(2x,/,15x,'THE SYSTEM DATA IS :',/,
1      4x,'THE order is ',i3,' the number of sub is ',i3)
      WRITE(23,512)
512      FORMAT(/,' THE WEIGHTS ARE: ')
      WRITE(23,413)(W(J),J=1,LLL)
      READ(22,414)(AL(J),J=1,ORDER)

```

```

414     FORMAT(10F)
      WRITE(23,515)
515     FORMAT(/, ' THE INDICES                THE EXPONENTS ')
      DO 119 J=1,ORDER
      READ(22,415)(IG(I,J),I=1,LLL)
      WRITE(23,416)J,(IG(I,J),I=1,12),AL(J)
415     FORMAT(13I)
416     FORMAT(13I3,F10.6)
119     CONTINUE
      DO 30 I=1,ORDER
      READ(22,125) OWINS(I),TRIALS(I)
30     CONTINUE
125     FORMAT(2F)
      WRITE(23,1225) (OWINS(I),I=1,ORDER)
1225    FORMAT(' WINS: ',15F7.3)
      WRITE(23,1226) (TRIALS(I),I=1,ORDER)
1226    FORMAT(' TRIALS: ',15F7.1)
      RETURN
      END

```

```

C***** XLAMBDA *****
C          THIS SOLVES EQUATION 1.4
C          TO FIND LAMBDA(DELTA)
C

```

```

C*****
      FUNCTION XLAMBD(TRIALS,PTILDE,PDELTA,I)
      DIMENSION TRIALS(100),PTILDE(100),PDELTA(100)
      S=0.
      DO 10 J=1,I
      IF(PTILDE(J).EQ.1.0)GOTO 10
      ZLOG1=ALOG(PDELTA(J)/PTILDE(J))
      ZLOG2=ALOG((1.-PDELTA(J))/(1.-PTILDE(J)))
      S=S+TRIALS(J)*(PTILDE(J)*ZLOG1+(1.-PTILDE(J))*ZLOG2)
10     CONTINUE
      XLAMBD=S
      RETURN
      END

```

```

C*****
C
C
C
C
C***** RELFUN *****
C          THIS IS THE REL. FUNCTION FOR PSEUDO-SERIES
C
C
C

```

```

      FUNCTION RELFUN(PROB)
      INCLUDE 'lcomp.f'
      DIMENSION PROB(100)
      INTEGER ORDER
      S1=0.0
      DO 100 L=1,LLL
      P1=1.0
      DO 90 J=1,ORDER
      P1=P1*PROB(J)**(AL(J)*IG(L,J))
90     CONTINUE
      S1=S1+W(L)*P1
100    CONTINUE
      RELFUN=S1
      RETURN
      END

```

ty Plrsub.for

```
C***** THIS IS THE SUBROUTINE PLRSUB *****
C      IT RUNS THE LIKELIHOOD RATIO METHOD
C      IT DOES NOT ADJUST THE FAILURES
C      IT WORKS ONLY FOR PSEUDO-SERIES.
C      ALL IS WORKING WELL WITH THE
C      SUBROUTINES POSDEL,CONMAP
C      WORKING ON THE VAX, 5/9/80
C*****
```

```
      SUBROUTINE PLRSUB(LCB)
      DIMENSION CHIISQ(3)
      INCLUDE 'lrcomp.for'
      INTEGER ORDER
      REAL LCB(3)
      DATA CHIISQ/.709, 1.074, 1.642/
C**** P GIVES US AN INITIAL INCREMENT BY WHICH WE CHANGE
C**** DELTA TO LOCALIZE ITS VALUE
      P=1.E15
      DO 40 I=1,ORDER
      IF(WINS(I).LE.P)P=WINS(I)
      PTILDE(I)=WINS(I)/TRIALS(I)
      PDELTA(I)=PTILDE(I)
40      CONTINUE
      P=P/10.0
      DELTA=P
      OLDLAM=0.0
      DO 50 I=1, 3
      Q=-1.0*CHIISQ(I)/2
      CALL POSDEL(BOUND,P,Q)
      BOUND=RELFUN(PDELTA)
      LCB(I)=BOUND
50      CONTINUE
      RETURN
999      END
```

C***** END OF PLRSUB *****

C
C
C
C

C***** POSDEL *****

```
C      POSDEL HAS TWO MAIN parts: in part 1 the value
C      of delta is incremented, with conmap finding
C      the vector of P(i)s, until q has been bracketed.
C      Once a vector of P(i)s is known we extrapolate
C      to get a new vector to start conmap with (the vector
C      corresponds to the new value of delta). This makes
C      conmap less likely to fail. If conmap fails the size
C      of the increment for delta is halved.
C      Part 2 interpolates to get a new delta and also
C      interpolates the P(i)s to set a corresponding vector
C      to start conmap. The interpolation is made possible
C      by storing the P(i)s that correspond to the upper
C      and lower bounds on Q.
```

```
C      JBL 3/6/80
C      NOW WORKING ON VAX 2/28/80
```

C*****

```
      SUBROUTINE POSDEL(BOUND,P,Q)
      INCLUDE 'lrcomp.FOR'
      DIMENSION UPBD(100),OLP(100)
      REAL LWBD(100)
      INTEGER ORDER
      LOGICAL FAIL
```

C***** INITIALIZING *****

GAP=P

DO 121 I=1,ORDER

LWBD(I)=0.0

UPBD(I)=PDELTA(I)

121

CONTINUE

FAIL=.FALSE.

C***** PART 1 *****

C START OF THE SEARCH FOR A SOLUTION REGION BY

C INCREMENTING DELTA BY GAP UNTIL THE SOLUTION IS BRACKETED

C

DO 20 J=1,200

OLAMB=OLDLAM

DELSAV=DELTA

DELTA=DELTA+GAP

IF(J.GT.1) THEN

C

***** here we extrapolate for pdelta *****

DO 1042 JJ=1,ORDER

PDELTA(JJ)=2*UPBD(JJ)-OLP(JJ)

IF(FAIL)PDELTA(JJ)=1.5*UPBD(JJ)-.5*OLP(JJ)

1042

CONTINUE

END IF

CALL CONMAP(FAIL,UPBD,LWBD,GAP)

1044

IF(FAIL) THEN

C

----- block 1-----

TYPE 9870

9870

format(' conmap failed ')

DELTA=DELTA-GAP

GAP=GAP/2.0

C

----- block 2 -----

ELSE

OLDLAM=XLAMB(TRIALS,PTILDE,PDELTA,ORDER)

C

+++++

IF(ABS(OLDLAM-Q).LT..001) RETURN

C

+++++

DO 19 JJ=1,ORDER

OLP(JJ)=UPBD(JJ)

IF(OLDLAM.LT.Q) LWBD(JJ)=PDELTA(JJ)

IF(OLDLAM.GT.Q) UPBD(JJ)=PDELTA(JJ)

19

CONTINUE

IF(OLDLAM.GT.Q)OLAMBU=OLDLAM

C

**** THIS IS OUR GOAL FOR THIS PART

IF(OLDLAM.LT.Q) GOTO 30

C

----- end of block 2 -----

END IF

20

CONTINUE

C

WRITE(5,2)

2

format(4x,'No solution after 100 steps in part 1.')

BOUND=.01

RETURN

C***** END OF PART 1 *****

C

C***** PART2 *****

C THIS IS THE START OF THE SECTION THAT SOLVES FOR

C DELTA USING THE REGULA FALSI METHOD

C AND we interpolate for the pdelta (between upbd

C and lwbd.).

C*****

C

**** INITIALIZE THE VARIABLES *****

30

deltau=delta-gap

deltal=delta

olamb1=oldlam

```

C      **** here we interpolate for delta and pdelta ****
      IF(.NOT.FAIL) RR=(Q-OLAMBU)/(OLAMBL-OLAMBU)
      IF(FAIL) RR=RR/2.0
      DELTA=DELTAU+RR*(DELTAI-DELTAU)
      DO 1313 JJ=1,ORDER
      PDELTA(JJ)=UPBD(JJ)+RR*(LWBD(JJ)-UPBD(JJ))
1313    CONTINUE
      GAPP=DELTAI-DELTAU
      -----
      CALL CONMAP(FAIL,UPBD,LWBD,GAPP)
      IF(.NOT.FAIL) THEN
C      ----- block 1 -----
      IT=0
9871    OLDLAM=XLAMBD(TRIALS,PTILDE,PDELTA,ORDER)
C      ++++++
      IF((OLDLAM-Q).lt..001)RETURN
C      ++++++
      IF(olddlam.lt.Q) THEN
C      --- block a ---
      DELTAI=DELTA
      OLAMBL=OLDLAM
      DO 38 JJ=1,order
      LWBD(JJ)=PDELTA(JJ)
38    CONTINUE
C      -----
      ELSE
C      --- block b ---
      DELTAU=DELTA
      OLAMBU=OLDLAM
      DO 39 JJ=1,ORDER
      UPBD(JJ)=PDELTA(JJ)
39    CONTINUE
C      -----
      END IF
C      **** CHECK TO SEE IF DELTAS ARE TOO CLOSE ****
      IF((deltai-deltau).lt.1E-5) then
      type 3
3    FORMAT(' DELTA CAN NO LONGER BE signif. INCREASED.')
      RETURN
      END IF
C      -----
      ELSE
C      -----CRISIS ROUTE -----
      IT=IT+1
      IF(IT.gt.9)stop
      END IF
C      -----
40    CONTINUE
      WRITE(5,1)
1    FORMAT(' NO SOLUTION FOUND AFTER 100 times thru part 2')
      BOUND=.01
      RETURN
C      ----- unsuccessful exit -----
      END
C***** END OF POSDEL *****
C-----
C
C
C+++++ CONMAP ++++++
C
C      THIS COMPUTES THE CONTRACTIVE MAP
C      OF EQN. 2.1 IN MYHRE-SAUNDERS PAPER.
C      THIS IS ONLY GOOD FOR PSEUDO-SERIES SYSTEMS
C      JBL 10/31/78
C      -----
C      UPDATED TO JUST KEEP A(J) BETWEEN THE

```


C BOUNDS ON PDELTA. JBL 2/16/80
 C***** CONMAP *****

SUBROUTINE CONMAP(FAIL,UPBD,LWBD,GAP)
 INCLUDE '1rcomp.FOR'
 INTEGER ORDER
 LOGICAL FAIL
 DIMENSION HOLD(100),A(100),UPBD(100)
 REAL LWBD(100)
 FAIL=.FALSE.
 TOL=.0005

C ***** IF GAP IS VERY SMALL WE SIMPLY AVERAGE THE BOUNDS OF PDELTA.
 IF(GAP.LT.1E-4)THEN
 DO 999 J=1,ORDER
 PDELTA(J)=(LWBD(J)+UPBD(J))/2.0
 999 CONTINUE
 RETURN

C -----
 ELSE
 C MAIN PART OF WORK.
 DO 10 J=1,ORDER
 HOLD(J)=PDELTA(J)
 A(J)=HOLD(J)
 10 CONTINUE
 C***** SOLVE THE CONTRACTIVE MAP
 DIST2=1.0
 100 DO 40 ICE=1,1000
 DIST=0.

C --- compute delay for each component -----
 DO 30 J=1,ORDER
 IF(WINS(J).EQ.TRIALS(J))A(J)=1.
 IF (A(J).NE.1.0) THEN
 AJP=0.0
 DO 25 L=1,LLL
 P1=1.0
 DO 26 JL=1,ORDER
 P1=P1*PDELTA(JL)**(AL(JL)*IG(L,JL))
 26 CONTINUE
 AJP=AJP+W(L)*AL(J)*IG(L,J)*P1
 25 CONTINUE
 DELAJ=DELTA*AJP
 C *** IF DELAJ>=WINS, DO NOT ASSIGN A(J), IT WILL BE NEG.
 IF(DELAJ.LT.WINS(J)) THEN
 A(J)=(WINS(J)-DELAJ)/(TRIALS(J)-DELAJ)
 C *** WE MUST MAKE SURE A(J).STAYS BETWEEN THE BOUNDS
 IF(A(J).LT.LWBD(J))A(J)=(PDELTA(J)+LWBD(J))/2.0
 IF(A(J).GT.UPBD(J))A(J)=(PDELTA(J)+UPBD(J))/2.0
 DIST=DIST+ABS(A(J)-PDELTA(J))
 C -----
 END IF

END IF
 30 CONTINUE

C ----- new pdeltas are done -----
 DO 70 L=1,ORDER
 PDELTA(L)=A(L)
 70 CONTINUE
 C ***** IF APPROXIMATIONS HAVE CONVERGED ENOUGH, WE STOP ITERATING.
 DIST=DIST/ORDER
 C ++++++
 IF(DIST.LT.TOL) RETURN
 C ++++++
 C ***** IF DIST IS INCREASING, CONMAP FAILS AND WE GO TRY
 C ***** ANOTHER DELTA AND KEEP THE OLD PDELTA'S.
 IF(DIST.LT.DIST2) THEN
 41 DIST2=DIST

```
ELSE
DO 50 J=1,ORDER
PDELTA(J)=HOLD(J)
FAIL=.TRUE.
RETURN
-----
END IF
40 CONTINUE
END IF
END
C*****
$
```

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